

**DISCRETIZATION of ONE-DIMENZIONAL
REACTION-DIFFUZION PROBLEM**

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ABSTRACT

For singularly perturbed selfadjoint one-dimenzional reaction-diffusion problem, using the Galerkin method with the natural choice of test function, a difference scheme on a non-uniform mesh is given, which is second-order accurate at nodes for the fixed perturbation parameter. A numerical example, which illustrating the theoretical results, is included.

Key words. Reaction-diffusion problem, difference scheme, Galerkin method .

1. INTRODUCTION

We consider the following two-point boundary value problem

$$L_\varepsilon y := \varepsilon^2 y''(x) - p(x)y(x) = f(x), \quad \text{na } (0,1) \quad (1)$$

$$y(0) = 0; \quad y(1) = 0, \quad (2)$$

where ε is parameter in $(0,1)$, while the functions p and f are in $C^2[0,1]$ and p satisfies

$$p(x) \geq \alpha > 0, \quad x \in [0,1]. \quad (3)$$

Under these hypotheses L_ε satisfies the maximum principle and problem (1)-(3) has a unique solution. The solution y has, in general, a boundary layer of width $O(\varepsilon)$ at both end points of $[0,1]$ (see [3]).

2. DISCRETIZATION OF THE PROBLEM

Let $0 = x_0 < x_1 < \dots < x_{n-1} < x_n = 1$ be a mesh on the interval $[0,1]$. The test functions ϕ_i ($i = 1, 2, \dots, n-1$) are taken, satisfying

$$\bar{L}_\varepsilon \phi_i = \varepsilon^2 \phi_i'' - \bar{p} \phi_i = 0, \quad \text{on } (x_j, x_{j+1}) \quad (j = 0, 1, \dots, n-1) \quad (4)$$

$$\phi_i(x_j) = \delta_{i,j} \quad (j = 0, 1, \dots, n-1), \quad (5)$$

where $\bar{p}(x) := \bar{p}_j = p(x_j + \frac{h_j}{2})$, on $[x_j, x_{j+1}]$ ($j = 0, 1, \dots, n-1$),

$$h_j = x_{j+1} - x_j \quad (j = 0, 1, \dots, n-1), \quad \text{and} \quad \bar{p}(x_n) = \bar{p}_{n-1}.$$

The test functions ϕ_i ($i = 1, 2, \dots, n-1$) have the form

$$\phi_i(x) = \begin{cases} u_{i-1}''(x) & ; \quad \text{if } x_{i-1} \leq x \leq x_i \\ u_i'(x) & ; \quad \text{if } x_i \leq x \leq x_{i+1} \\ 0 & ; \quad \text{otherwise} \end{cases},$$

where

$$u_i'(x) = \frac{\sinh(\beta_i(x_{i+1} - x))}{\sinh(\beta_i h_i)}; \quad u_i''(x) = \frac{\sinh(\beta_i(x - x_i))}{\sinh(\beta_i h_i)},$$

$$\beta_i = \frac{\sqrt{\bar{p}_i}}{\varepsilon}, \quad h_i = x_{i+1} - x_i, \quad (i = 0, 1, \dots, n-1).$$

The approximate solution is then sought in the form $\bar{y}^h(x) = \sum_{k=1}^{n-1} \bar{y}_k^h \phi_k(x); \quad \bar{y}_o^k = \bar{y}_n^k = 0.$

Using the properties of the basis functions ϕ_k ($k = 1, 2, \dots, n-1$), it is evident that $\bar{y}^h(x_k) = \bar{y}_k^h$ ($k = 1, 2, \dots, n-1$). If we define the operator

$$\bar{B}_\varepsilon(w, v) := (-\varepsilon^2 w', v') - (\bar{p}w, v), \quad (w, v \in H_0^1), \quad (6)$$

then we can find the set of constants \bar{y}_k^h ($k = 1, 2, \dots, n-1$) from the following system of linear equations

$$\bar{a}_{i,i-1}^h \bar{y}_{i-1}^h + \bar{a}_{i,i} \bar{y}_i^h + \bar{a}_{i,i+1}^h \bar{y}_{i+1}^h = (\bar{f}, \phi_i) \quad (i = 1, 2, \dots, n-1) \quad (7)$$

where $\bar{a}_{i,k} = \bar{B}_\varepsilon(\phi_k, \phi_i)$ ($k = i-1, i, i+1$) and $\bar{f}(x)$ is defined analogously to $\bar{p}(x)$.

Lemma 1. The difference scheme (7) has a unique solution.

Proof. The matrix of the difference scheme (7) is an M-matrix, and hence invertible. Δ

Let $\tilde{p}(x)$ and $\tilde{f}(x)$ be continuous piecewise linear Lagrangian interpolants of $p(x)$ and $f(x)$ on $[0,1]$, respectively. So, we have

$$\begin{aligned} \tilde{p}(x) &= \tilde{p}_i = a_i x + b_i \quad \text{on } [x_i, x_{i+1}], \\ \tilde{f}(x) &= \tilde{f}_i = c_i x + d_i \quad \text{on } [x_i, x_{i+1}]. \end{aligned}$$

The approximate solution is then sought in the form

$$\tilde{y}^h(x) = \sum_{k=1}^{n-1} \tilde{y}_k^h \phi_k(x); \quad \tilde{y}_o^k = \tilde{y}_n^k = 0, \quad (8)$$

Using the properties of the basic functions ϕ_k ($k = 1, 2, \dots, n-1$), it is evident $\tilde{y}^h(x_k) = \tilde{y}_k^h$ ($k = 1, 2, \dots, n-1$). If we define the operator

$$\tilde{B}_\varepsilon(w, v) := (-\varepsilon^2 w', v') - (\tilde{p}w, v), \quad (w, v \in H_0^1), \quad (9)$$

then we can find the set of constants \tilde{y}_k^h ($k = 1, 2, \dots, n-1$) from

$$\tilde{B}_\varepsilon(\tilde{y}^h, \phi_i) = (\tilde{f}, \phi_i), \quad \text{for } i = 1, 2, \dots, n-1. \quad (10)$$

from (10) we have following variational difference scheme

$$\tilde{a}_{i,i-1}^h \tilde{y}_{i-1}^h + \tilde{a}_{i,i} \tilde{y}_i^h + \tilde{a}_{i,i+1}^h \tilde{y}_{i+1}^h = (\tilde{f}, \phi_i) \quad (i = 1, 2, \dots, n-1), \quad (11)$$

where $\tilde{a}_{i,k} = \tilde{B}_\varepsilon(\phi_k, \phi_i)$ ($k = i-1, i, i+1$). Now, we have

$$\tilde{a}_{i,k} = \bar{B}_\varepsilon(\phi_k, \phi_i) - ((\tilde{p} - \bar{p})\phi_k, \phi_i) = \bar{a}_{i,k} - ((\tilde{p} - \bar{p})\phi_k, \phi_i) \quad \text{for } k = i-1, i, i+1. \quad (12)$$

3. NUMERICAL EXPERIMENT

In this section, we present some numerical results which illustrate the results in section 2. The maximum error E_n between analytic solution and numerical solution, i.e.

$E_n = \max_{0 \leq i \leq n} |y(x) - \bar{y}^h(x)|$ for scheme (7) and $E_n = \max_{0 \leq i \leq n} |y(x) - \tilde{y}^h(x)|$ for scheme (11).

The order of convergence, defined in the usual way by $Ord = \frac{\ln(E_n) - \ln(E_{2n})}{\ln 2}$.

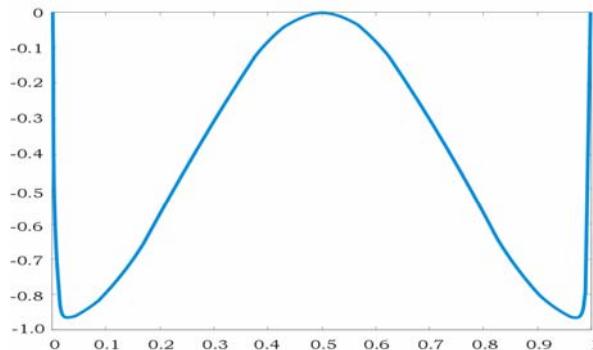
Example. In this example we apply the difference schemes (7) and (11) to problem

$$\varepsilon^2 y'' - y = \cos^2 \pi x + 2\varepsilon^2 \pi^2 \cos 2\pi x$$

$$y(0) = 0 \quad ; \quad y(1) = 0 .$$

The analytic solution of this problem can be written explicitly as $y(x) = \frac{e^{-\frac{x}{\varepsilon}} + e^{\frac{x-1}{\varepsilon}}}{1 + e^{\frac{-1}{\varepsilon}}} - \cos^2 \pi x .$

$$y(x) \text{ za } \varepsilon^2 = 2^{-16}$$



It can be seen from the form of the analytic solution that this problem has a boundary layers in the neighbourhood of points $x=0$ and $x=1$ for small parameter ε .

In this case we let $h = n^{-1}$; $\varepsilon^2 = 2^{-k}$

Table 1. Scheme (7)

n \ k	3	4	5	6	7	8	10	12	
16	1.86e-2 1.99	1.62e-2 1.99	1.43e-2 1.99	1.33e-2 1.99	1.30e-2 2.00	1.31e-2 2.02	1.38e-2 2.07	1.57e-2 2.17	E _n Ord
	4.68e-3 1.99	4.06e-3 1.99	3.59e-3 1.99	3.33e-3 1.99	3.24e-3 2.01	3.23e-3 2.02	3.28e-3 2.08	3.48e-3 2.08	E _n Ord
32	1.17e-3 2.00	1.01e-3 2.00	8.97e-4 2.00	8.32e-4 2.00	8.09e-4 2.00	8.04e-4 2.00	8.07e-4 2.02	8.22e-4 2.03	E _n Ord
	2.92e-4 2.00	2.54e-4 2.00	2.24e-4 2.00	2.08e-4 2.00	2.02e-4 2.00	2.01e-4 2.00	2.01e-4 2.00	2.02e-4 2.03	E _n Ord
128	7.32e-5 2.00	6.35e-5 2.00	5.61e-5 2.00	5.20e-5 2.00	5.05e-5 1.99	5.02e-5 1.99	5.02e-5 1.99	5.02e-5 2.00	E _n Ord
	1.83e-5 2.00	1.58e-5 2.00	1.40e-5 2.00	1.30e-5 2.00	1.26e-5 2.00	1.25e-5 1.99	1.25e-5 1.99	1.25e-5 2.00	E _n Ord
512	4.56e-6 2.00	4.00e-6 2.00	3.50e-6 2.00	3.24e-6 2.00	3.15e-6 2.00	3.13e-6 1.99	3.13e-6 1.99	3.13e-6 2.00	E _n Ord
1024									E _n

Table 2. Scheme (11)

n \ k	3	4	5	6	7	8	10	12	
16	9.29e-3 1.99	8.06e-3 1.99	7.11e-3 1.99	6.58e-3 1.99	6.36e-3 1.98	6.27e-3 1.98	5.97e-3 1.93	5.11e-3 1.77	E _n Ord
	2.33e-3 1.99	2.02e-3 1.99	1.79e-3 1.99	1.66e-3 2.00	1.61e-3 1.99	1.59e-3 1.99	1.57e-3 1.98	1.50e-3 1.93	E _n Ord
32	5.85e-4 2.00	5.08e-4 2.00	4.48e-4 2.00	4.15e-4 2.00	4.04e-4 2.00	4.01e-4 2.00	3.99e-4 2.00	3.94e-4 1.98	E _n Ord
	1.46e-4 2.00	1.27e-4 2.00	1.12e-4 2.00	1.04e-4 2.00	1.01e-4 2.00	1.00e-4 2.00	1.00e-4 2.00	1.00e-4 2.00	E _n Ord
256	3.66e-5 2.00	3.17e-5 2.00	2.80e-5 2.00	2.60e-5 2.00	2.52e-5 2.00	2.51e-5 2.00	2.50e-5 2.00	2.50e-5 2.00	E _n Ord
	9.15e-6 2.00	7.94e-6 2.00	7.01e-6 2.00	6.50e-6 2.00	6.31e-6 2.00	6.27e-6 2.00	6.27e-6 2.00	6.27e-6 2.00	E _n Ord
512	2.28e-6 2.00	1.98e-6 2.00	1.74e-6 2.00	1.62e-6 2.00	1.58e-6 2.00	1.57e-6 1.99	1.57e-6 1.99	1.57e-6 2.00	E _n Ord
1024									E _n

Comparing Table 1 with Table 2 one can see that the errors in Table 2 are about two Times smaller then the coresponding errors in Table 1. The numerical results in Tables indicate the uniform convergence of the difference schemes (7) and (11) at the rate $O(h^2)$.

4. REFERENCES

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